

TRANSMITTAL LETTER TO THE UNITED STATES  
DESIGNATED/ELECTED OFFICE (DO/EO/US)  
CONCERNING A FILING UNDER 35 U.S.C. 371INTERNATIONAL APPLICATION NO.  
PCT/JP00/01510INTERNATIONAL FILING DATE  
MARCH 13, 2000

U.S. APPLICATION NO. (If known see 37 C.F.R. 1.5)

09/700168

(EARLIEST) PRIORITY DATE CLAIMED  
MARCH 12, 1999

TITLE OF INVENTION

DATA PROCESSING APPARATUS, DATA PROCESSING METHOD  
AND MEDIUM

APPLICANT(S) FOR DO/EO/US

Tetsujiro KONDO and Junichi ISHIBASHI

Applicants herewith submit to the United States Designated/Elected Office (DO/EO/US) the following items and other information:

1.  This is a **FIRST** submission of items concerning a filing under 35 U.S.C. 371.
2.  This is a **SECOND** or **SUBSEQUENT** submission of items concerning a filing under 35 U.S.C. 371.
3.  This is an express request to promptly begin national examination procedures (35 U.S.C. 371(f)).
4.  The US has been elected by the expiration of 19 months from the priority date (PCT Article 31).
5.  A copy of the International Application as filed (35 U.S.C. 371(c)(2))
  - a.  is attached hereto (required only if not communicated by the International Bureau).
  - b.  has been communicated by the International Bureau.
  - c.  is not required, as the application was filed in the United States Receiving Office (RO/US).
6.  An English language translation of the International Application as filed (35 U.S.C. 371(c)(2)).
7.  Amendments to the claims of the International Application under PCT Article 19 (35 U.S.C. 371(c)(3))
  - a.  are attached hereto (required only if not communicated by the International Bureau).
  - b.  have been communicated by the International Bureau.
  - c.  have not been made; however, the time limit for making such amendments has NOT expired.
  - d.  have not been made and will not be made.
8.  An English language translation of the amendments to the claims under PCT Article 19 (35 U.S.C. 371(c)(3)).
9.  An oath or declaration of the inventor(s) (35 U.S.C. 371(c)(4)).
10.  An English language translation of the annexes to the International Preliminary Examination Report under PCT Article 36 (35 U.S.C. 371(c)(5)).

## Items 11 to 16 below concern document(s) or information included:

11.  An Information Disclosure Statement under 37 CFR 1.97 and 1.98.
12.  An assignment document for recording. A separate cover sheet in compliance with 37 CFR 3.28 and 3.31 is included.
13.  A **FIRST** preliminary amendment.
14.  A **SECOND** or **SUBSEQUENT** preliminary amendment.
15.  A substitute specification.
16.  A change of power of attorney and/or address letter.
17.  Other items or information:

PCT/RO/101, PCT/IB/301,304,308

PCT/ISA/220, 210

19 Sheets of Drawings, 1 Page of Abstract

## EXPRESS MAIL

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U.S. APPLICATION NO (if known, see 37 C.F.R. 1.50)

INTERNATIONAL APPLICATION NO.

09/700168

PCT/JP00/01510

ATTORNEY'S DOCKET NO

450101-02398

(CALCULATIONS /PTO USE ONLY)

17.  The following fees are submitted**Basic National Fee (37 CFR 1.492(a)(1)-(5):**

Neither international preliminary examination fee (37 CFR 1.482)  
 nor international search fee (37 CFR 1.445(a)(2) paid to USPTO  
 and International Search Report not prepared by the EPO or JPO..... \$1,000.00

International preliminary examination fee (37 CFR 1.482) not paid to  
 USPTO but International Search Report prepared by the EPO or JPO..... \$ 860.00

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International preliminary examination fee paid to USPTO (37 CFR 1.482)  
 but all claims did not satisfy provisions of PCT Article 33(1)-(4)..... \$ 690.00

International preliminary examination fee paid to USPTO (37 CFR 1.482)  
 and all claims satisfied provisions of PCT Article 33(1)-(4)..... \$ 100.00

**ENTER APPROPRIATE BASIC FEE AMOUNT = (\$ 860.00)**

Surcharge of **\$130.00** for furnishing the oath or declaration later than  20  30 (\$  
 months from the earliest claimed priority date (37 CFR 1.492(e)).

33 Claims /Number Filed / Number Extra /Rate (\$

Total Claims / 33 - 20 = / 13 /X \$18.00 (\$ 234.00

Independent Claims / 21 - 3 = / 18 /X \$80.00 (\$1,440.00

MULTIPLE DEPENDENT CLAIM(S) (if applicable) /+ \$270.00 (\$

**TOTAL OF ABOVE CALCULATIONS = (\$2,534.00)**

Applicant claims small entity status. See 37 C.F.R. 1.27. The fees indicated above  
 are reduced by ½. (\$

**SUBTOTAL = (\$2,534.00)**

Processing fee of **\$130.00** for furnishing the English translation later than  20  30 (\$  
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**TOTAL NATIONAL FEE = (\$2,534.00)**

Fee for recording the enclosed assignments (37 CFR 1.21(h)). The assignment must be (\$ 40.00  
 accompanied by an appropriate cover sheet (37 CFR 3.28, 3.31). \$40.00 per property + (\$

**TOTAL FEES ENCLOSED = (\$2,574.00)**

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NOTE: Where an appropriate time limit under 37 CFR 1.494 or 1.495 has not been met, a petition to revive (37 CFR 1.137(a) or (b)) must be filed and granted to restore the application to pending status.

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Dated: November 9, 2000

  
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25,506

REGISTRATION NUMBER

Description

Data Processing Apparatus, Data Processing Method and Recording Medium

Technical Field

This invention relates to a representative sample generating apparatus, a representative sample generating method, a classification apparatus, a classification method, a coefficient data generating apparatus, a coefficient data generating method, a sample feature data generating apparatus, a sample feature data generating method, a data processing apparatus, a data processing method and a recording medium.

Background Art

There is disclosed a method of detecting the orientation of a face of a human being as an object in D-596 "real-time extraction of an image of a human being oriented in a specified direction" on p7 to 308, Extended Abstract to National Spring Meeting of the Telecommunication Science Association, 1991. In this method, a human face is imaged with a monochromatic camera, and the resulting image data is binary-coded and a human being whose face is directed to the front side is retrieved based on the distance between the center of an area containing eyes, a nose and a mouth and the center of a head. There is also disclosed a method entitled: "application to a command input of a method for detecting a face orientation by an image seen with a sole eye" in a thesis journal D-11 vol.J72-D-II Mo.9 pages 1441 to 1447, of the

Telecommunication Science Association, September 1989. In this method, a human face is modelled as a triangle constituted by three characteristic points, with distances between respective three points being given as known data. From the projection between these three points, the positions of the point of gravity of the triangle and the direction of the normal line are detected as the face orientation in a three-dimensional space.

In the Japanese Laying-Open Patent H-7-23934, it is proposed to find the orientation of the face based on the ratio  $L/W$  between the width  $L$  of the left head hair area  $L$  and the width  $W$  of the face area and on the ratio  $L/R$  between the width  $L$  of the right head hair area and the width  $R$  of the right head hair area.

However, if, when the characteristic points of the human face are both eyes and the nose etc, the face is movable over a wide range, both eyes become undetectable when the face is turned beyond a certain threshold angle, as a result of which characteristic points of the human face become unmeasurable.

Moreover, it is difficult to detect the positions of both eyes and the mouth from the head automatically and robustly. Moreover, in the latter method, in which the limiting conditions that the distances of the three points are known from the outset, it becomes difficult to automate the processing.

In the method described in Japanese Laying-Open Patent H-7-23934, in which the image is acquired using an IR camera, it is not only impossible to guess the face orientation from the image photographed using a routine camera, but the cost is

raised significantly.

#### Disclosure of the Invention

Meanwhile, it is not too much to say that a sensor is general is a device for verifying the similarity. For example, a thermometer compares the current temperature with a previously measured reference temperature to output the closest temperature. The same may apply for the speedometer or an angle gauge. Although these devices give sensor outputs from the point information, the same may be said of sensors handling the non-point information employing the past and future information. Representative of this sort of the sensor is an image sensor. In a majority of sensors, which sense the input image to verify what is the projected object, a previously formed template is compared to an input image to select the most analogous image as a response. In this technique, in which a fixed template is used as a template for comparing input data, it has been difficult to verify which template is to be used to give an optimum decision. It has also been difficult to verify how many templates are to be used to give optimum results.

It is therefore an object of the present invention to enable an optimum template to be produced.

If a grouping operation is to be performed in which an input to a pre-set fixed processing is to be outputted to a classified group, it is difficult to establish an optimum classification method from the outset. Moreover, if the population is

deviated at the time of execution from the presumed population, and the processing is a fixed processing, this state cannot be coped with.

It is therefore another object of the present invention to allow for flexible accommodation to the conversion of the population and to enable an optimum classification method to be obtained automatically.

It should be noted that the real world is more replete with non-linear objects, than linear objects. Since linear prediction equations are mainly used for prediction, there is raised no problem if the linear objects only are present in the same class, however, if non-linear objects are included in the same class, and the least square approximation is used in learning, over-fitting, for example, may be produced due to the influence of the non-linear elements, thus leading to the problem that the performance is lowered despite the fact that the number of orders of the prediction equation is increased. There is also raised a problem that an error ascribable to the use of the approximation may occasionally be increased to affect the performance.

It is therefore yet another object of the present invention to reduce the influence of the non-linear elements.

In view of the above-described status of the art, the present invention contemplates to enable the orientation of an object, such as a face orientation, to be estimated accurately over a wide range from an image photographed by a video camera.

According to the present invention, there is provided a representative sample

generating apparatus for generating representative sample data of a plurality of groups, based on a plurality of sample data initially classified into the plural groups, in which the apparatus includes group feature data detection means for detecting group feature data representing feature of sample data in each of the groups, distance detection means for detecting the distances between all of the sample data and the group feature data of each group, re-classification means for re-classifying all of the sample data into the plural groups based on the distances, convergence detection means for detecting whether or not the number of sample data classified into groups different from previous groups is converged as a result of re-classification by the re-classification means and decision means for repeating the processing by the group feature data detection means, re-classification means and the convergence detection means until the convergence detection means has detected convergence, and for determining the group feature data of each group prevailing at the time of the convergence as detected by the convergence detection means as representative sample data of each group.

According to the present invention, there is also provided a representative sample generating method for generating representative sample data of a plurality of groups, based on a plurality of sample data initially classified into the plural groups, in which the method includes a step of detecting group feature data representing feature of sample data in each of the groups, a step of detecting the distances between all of the sample data and the group feature data of each group, a step of re-classifying all of the sample data into the plural groups based on the distances, a step of detecting

whether or not the number of sample data classified into groups different from previous groups is converged as a result of re-classification by the re-classification step and a step of repeating the processing by the group feature data detection step, re-classification step and the convergence detection step until the convergence detection step has detected convergence, and for determining the group feature data of each group prevailing at the time of the convergence as detected by the convergence detection step as representative sample data of each group.

According to the present invention, there is also provided a recording medium having recorded thereon a computer-controllable program for performing representative sample generating processing for generating representative sample data of a plurality of groups, based on a plurality of sample data initially classified into the plural groups, in which the program includes a step of detecting group feature data representing feature of sample data in each of the groups, a step of detecting the distances between all of the sample data and the group feature data of each group, a step of re-classifying all of the sample data into the plural groups based on the distances, a step of detecting whether or not the number of sample data classified into groups different from previous groups is converged as a result of re-classification by the re-classification step, and a step of repeating the processing by the group feature data detection step, re-classification step and the convergence detection step until the convergence detection step has detected convergence, and for determining the group feature data of each group prevailing at the time of the convergence as detected by the

convergence detection step as representative sample data of each group.

According to the present invention, there is also provided a representative sample generating apparatus for generating representative sample data of each of a plurality of groups by classifying the plural sample data, having appended supplementary data indicating respective feature, into the plural groups, in which the apparatus includes initial classification means for initially classifying the plural sample data into plural groups, based on the supplementary data, group feature data detection means for detecting group feature data representing feature of the sample data in each of the groups, distance detection means for detecting the distances between all of the sample data and the group feature data of each group, re-classification means for re-classifying all of the sample data into the plural groups based on the distances, convergence detection means for detecting whether or not the number of sample data classified into groups different from previous groups is converged as a result of re-classification by the re-classification means, and decision means for repeating the processing by the group feature data detection means, the re-classification means and the convergence detection means until the convergence detection means has detected convergence, and for determining the group feature data of each group prevailing at the time of the convergence as detected by the convergence detection means as representative sample data of each group.

According to the present invention, there is also provided a representative sample generating method for generating representative sample data of each of a

plurality of groups by classifying the plural sample data, having appended supplementary data indicating respective feature, into the plural groups, in which the method includes a step of initially classifying the plural sample data into plural groups, based on the supplementary data, a step of detecting group feature data representing feature of the sample data in each of the groups, a step of detecting the distances between all of the sample data and the group feature data of each group, a step of re-classifying all of the sample data into the plural groups based on the distances, a step of detecting whether or not the number of sample data classified into groups different from previous groups is converged as a result of re-classification by the re-classification step and a step of repeating the processing by the group feature data detection step, the re-classification step and the convergence detection step until the convergence detection step has detected convergence, and of determining the group feature data of each group prevailing at the time of the convergence as detected by the convergence detection step as representative sample data of each group.

According to the present invention, there is also provided a recording medium having recorded thereon a computer-controllable program for generating representative sample data of each of a plurality of groups by classifying the plural sample data, having appended supplementary data indicating respective feature, into the plural groups, in which the program includes a step of initially classifying the plural sample data into plural groups, based on the supplementary data, a step of detecting group feature data representing feature of the sample data in each of the

groups, a step of detecting the distances between all of the sample data and the group feature data of each group, a step of re-classifying all of the sample data into the plural groups based on the distances, a step of detecting whether or not the number of sample data classified into groups different from previous groups is converged as a result of re-classification by the re-classification step and a step of repeating the processing by the group feature data detection step, the re-classification step and the convergence detection step until the convergence detection step has detected convergence, and of determining the group feature data of each group prevailing at the time of the convergence as detected by the convergence detection step as representative sample data of each group.

According to the present invention, there is also provided a classification apparatus for re-classifying sample data initially classified into a plurality of groups, in which the apparatus includes group feature data detection means for detecting group feature data representing feature of the sample data for each of the groups, distance detection means for detecting the distances between all of the sample data and the group feature data of each group, re-classification means for re-classifying all of the sample data into the plural groups based on the distances, convergence detection means for detecting whether or not the number of sample data classified into groups different from previous groups is converged as a result of re-classification by the re-classification means and decision means for repeating the processing by the group feature data detection means, the re-classification means and the convergence

detection means until the convergence detection means has detected convergence, and for determining the results of re-classification of each sample data by the re-classification means on convergence detection by the convergence detection means.

According to the present invention, there is provided a classification method for re-classifying sample data initially classified into a plurality of groups, in which the method includes a step of detecting group feature data representing feature of the sample data for each of the groups, a step of detecting the distances between all of the sample data and the group feature data of each group, a step of re-classifying all of the sample data into the plural groups based on the distances, a step of detecting whether or not the number of sample data classified into groups different from previous groups is converged as a result of re-classification by the re-classification step and a step of repeating the processing by the group feature data detection step, the re-classification step and the convergence detection step until the convergence detection step has detected convergence, and of determining the results of re-classification of each sample data by the re-classification step on convergence detection by the convergence detection step.

According to the present invention, there is also provided a recording medium having recorded thereon a computer-controllable program for performing processing of re-classifying a plurality of sample data, based on a plurality of sample data initially classified into plural groups, in which the program includes a step of detecting group feature data representing feature of sample data in each of the groups, a step of

detecting the distances between all of the sample data and the group feature data of each group, a step of re-classifying all of the sample data into the plural groups based on the distances, a step of detecting whether or not the number of sample data classified into groups different from previous groups is converged as a result of re-classification by the re-classification step and a step of repeating the processing by the group feature data detection step, re-classification step and the convergence detection step until the convergence detection step has detected convergence, and of determining the results of re-classification of each sample data by the re-classification step on convergence detection in the convergence detection step as ultimate results of classification of each of the groups.

According to the present invention, there is also provided a classification apparatus for classifying plural sample data, having appended supplementary data indicating respective feature, into plural groups, in which the apparatus includes initial classification means for initially classifying the plural sample data into plural groups, based on the supplementary data, group feature data detection means for detecting group feature data representing feature of the sample data in each of the groups, distance detection means for detecting the distances between all of the sample data and the group feature data of each group, re-classification means for re-classifying all of the sample data into the plural groups based on the distances, convergence detection means for detecting whether or not the number of sample data classified into groups different from previous groups is converged as a result of re-classification by the re-

classification means, and decision means for repeating the processing by the group feature data detection means, the re-classification means and the convergence detection means until the convergence detection means has detected convergence, and for determining the results of re-classification of each sample data by the re-classification means on convergence detection in the convergence detection step as ultimate results of classification of each of the groups.

According to the present invention, there is also provided a classification method for classifying plural sample data, having appended supplementary data indicating respective feature, into plural groups, in which the method includes a step of initially classifying the plural sample data into plural groups, based on the supplementary data, a step of detecting group feature data representing feature of the sample data in each of the groups, a step of detecting the distances between all of the sample data and the group feature data of each group, a step of re-classifying all of the sample data into the plural groups based on the distances, a step of detecting whether or not the number of sample data classified into groups different from previous groups is converged as a result of re-classification by the re-classification step and a step of repeating the processing by the group feature data detection step, the re-classification step and the convergence detection step until the convergence detection step has detected convergence, and of determining the results of re-classification of each sample data by the re-classification step on convergence detection in the convergence detection step as ultimate results of classification of each of the groups.

According to the present invention, there is also provided a recording medium having recorded thereon a computer-controllable program for classifying plural sample data, having appended supplementary data indicating respective feature, into plural groups, in which the program includes a step of initially classifying the plural sample data into plural groups, based on the supplementary data, a step of detecting group feature data representing feature of the sample data in each of the groups, a step of detecting the distances between all of the sample data and the group feature data of each group, a step of re-classifying all of the sample data into the plural groups based on the distances, a step of detecting whether or not the number of sample data classified into groups different from previous groups is converged as a result of re-classification by the re-classification step and a step of repeating the processing by the group feature data detection step, the re-classification step and the convergence detection step until the convergence detection step has detected convergence, and of determining the results of re-classification of each sample data by the re-classification step on convergence detection in the convergence detection step as ultimate results of classification of each of the groups.

According to the present invention, there is also provided a coefficient data generating apparatus for generating a coefficient data set adapted for generating sample feature data from new sample data not having sample feature data, based on a database in which there are pre-stored the sample feature data and sample data associated with the sample feature data, in which the apparatus includes classification

means for classifying the sample data into a plurality of classes, based on the relation thereof with representative sample data which is set to each classification and which is associated with the sample feature data, means for generating, for each class, a normal equation having the values of the sample feature data and the sample data as previously known data and having coefficient data as unknown data and coefficient data generating means for solving the normal equation for each class to generate the coefficient data set for each class.

According to the present invention, there is provided a coefficient data generating method for generating a coefficient data set adapted for generating sample feature data from new sample data not having sample feature data, based on a database in which there are pre-stored the sample feature data and sample data associated with the sample feature data, in which the method includes a step of classifying the sample data into a plurality of classes, based on the relation thereof with representative sample data which is set to each classification and which is associated with the sample feature data, a step of generating, for each class, a normal equation having the values of the sample feature data and the sample data as previously known data and having coefficient data as unknown data and a step of solving the normal equation for each class to generate the coefficient data set for each class.

According to the present invention, there is provided a recording medium having recorded thereon a computer-controllable program adapted for generating a coefficient data set adapted for generating sample feature data from new sample data

not having sample feature data, based on a database in which there are pre-stored the sample feature data and sample data associated with the sample feature data, in which the program includes a step of classifying the sample data into a plurality of classes, based on the relation thereof with representative sample data which is set to each classification and which is associated with the sample feature data, a step of generating, for each class, a normal equation having the values of the sample feature data and the sample data as previously known data and having coefficient data as unknown data and a step of solving the normal equation for each class to generate the coefficient data set for each class. According to the present invention, there is also provided a sample feature data generating apparatus including distance detection means for detecting distance between input sample data and each representative sample data generated previously for each of a plurality of groups, classification means for classifying the input sample data into one of the classes, based on the distances of the input sample data from representative sample data of the plural groups and sample feature data generating means for generating sample feature data representing the feature of the input sample data in accordance with a system pre-set for each class.

According to the present invention, there is also provided a sample feature data generating method including a step of detecting distance between input sample data and each representative sample data generated previously for each of a plurality of groups,

a step of classifying the input sample data into one of the classes, based on the

distances of the input sample data from representative sample data of the plural groups and a step of generating sample feature data representing the feature of the input sample data in accordance with a system pre-set for each class.

According to the present invention, there is also provided a recording medium having recorded thereon a computer-controllable program adapted for generating sample feature data representing feature of input sample data, in which the program includes a step of detecting distance between input sample data and each representative sample data generated previously for each of a plurality of groups, a step of classifying the input sample data into one of the classes, based on the distances of the input sample data from representative sample data of the plural groups and a step of generating sample feature data representing the feature of the input sample data in accordance with a system pre-set for each class.

According to the present invention, there is also provided a data processing apparatus including a representative sample generating device adapted for repeatedly performing the operations of detecting group feature data based on a plurality of sample data initially classified into a plurality of groups, the group feature data representing feature of sample data in each of the groups, detecting distances between all of the sample data and the group feature data of each group, re-classifying all of the sample data into the plural groups, based on the detected distance, and detecting whether or not the number of sample data classified into groups different from the previous groups has converged, and for determining the group feature data of each

group prevailing on detection of the convergence by the re-classification of the number of sample data classified into groups different from the previous group, as representative sample data of each group; and a sample feature data generating device adapted for detecting the distances of input sample data to representative sample data of each group, classifying the input sample data into one of a plurality of classes, based on the distances of the input sample data to the representative sample data of each group, and for generating sample feature data representing feature of the input sample data in accordance with a system pre-set for each class.

According to the present invention, there is also provided a data processing method including a step of repeatedly performing the operations of detecting group feature data based on a plurality of sample data initially classified into a plurality of groups, the group feature data representing feature of sample data in each of the groups, detecting distances between all of the sample data and the group feature data of each group, re-classifying all of the sample data into the plural groups, based on the detected distance, and detecting whether or not the number of sample data classified into groups different from the previous groups has converged, and for determining the group feature data of each group prevailing on detection of the convergence by the re-classification of the number of sample data classified into groups different from the previous group, as representative sample data of each group, and a step of detecting the distances of input sample data to representative sample data of each group, classifying the input sample data into one of a plurality of classes, based on the

distances of the input sample data to the representative sample data of each group, and of generating sample feature data representing feature of the input sample data in accordance with a system pre-set for each class.

According to the present invention, there is also provided a recording medium having recorded thereon a computer-controllable program adapted for performing the processing of generating sample feature data representing feature of input sample data, in which the program includes a step of repeatedly performing the operations of detecting group feature data based on a plurality of sample data initially classified into a plurality of groups, the group feature data representing feature of sample data in each of the groups, detecting distances between all of the sample data and the group feature data of each group, re-classifying all of the sample data into the plural groups, based on the detected distance, and detecting whether or not the number of sample data classified into groups different from the previous groups has converged, and determining the group feature data of each group prevailing on detection of the convergence by the re-classification of the number of sample data classified into groups different from the previous group, as representative sample data of each group, and a step of detecting the distances of input sample data to representative sample data of each group, classifying the input sample data into one of a plurality of classes, based on the distances of the input sample data to the representative sample data of each group, and of generating sample feature data representing feature of the input sample data in accordance with a system pre-set for each class.

### Brief Description of the Drawings

Fig.1 is a block diagram showing an illustrative structure of an image processing apparatus according to the present invention.

Fig.2 is a block diagram showing a functional structure of a processing device in the image processing apparatus.

Fig.3 is a flowchart for illustrating the operation of the image processing apparatus.

Fig.4 shows an example of a database.

Fig.5 is a flowchart showing the processing for preparing images of three representative faces in the image processing apparatus.

Figs.6A to 6C schematically show an example of templates having different shapes of the effective area.

Fig.7 illustrates the averaging processing of the template.

Fig.8 illustrates the averaging processing of the template.

Fig.9 illustrates the averaging processing of the template.

Fig.10 illustrates images of three representative faces.

Fig.11 shows the relation between the image of the representative faces and associated templates.

Fig.12 is a flowchart showing another example of the processing for preparing images of the representative faces.

Fig.13 shows the relation between the images of the three representative faces

and the associated templates in the initial classification processing.

Fig.14 is a flowchart showing the face position decision processing by the image processing apparatus.

Figs.15A and 15B illustrate images of the representative faces which give the maximum correlation with the input image.

Fig.16 illustrates the post-search correlative values.

Fig.17 schematically shows the correlative values in three-dimensional representation wherein the high correlative value portions are shown to an enlarged scale.

Fig.18 is a flowchart showing the face angle decision processing in the image processing apparatus.

Fig.19 shows the relation between the object angle and the correlative values.

Fig.20 illustrates an input image and the image of the representative face having the maximum correlation with the input image.

Fig.21 illustrates an input image and the image of the representative face having the maximum correlation with the input image.

Fig.22 illustrates the relation between the input image and the face class.

Fig.23 is a flowchart showing the class decision processing for classification into classes.

Fig.24 is a flowchart showing another example of the class decision processing for classification into classes.

Fig.25 is a flowchart showing prediction coefficient decision processing.

Fig.26 is a block diagram showing a computer system used as a calculating device in the image processing apparatus.

#### Best mode for Carrying out the Invention

Referring to the drawings, a best mode for carrying out the present invention is explained in detail.

The present invention is applied to a contents selection system configured as shown for example in Fig.1.

Fig.1 shows an illustrative structure of an image processing apparatus embodying the present invention. An image processing apparatus 1 is constituted by e.g., a video camera, and images an object. An A/D converter 2 A/D converts image data outputted by the image processing apparatus 1 to send the converted image data to a processing device 3. A memory device 4 is constituted e.g., by a hard disc and stores image data processed by a processing device 3 and image data as templates.

The processing device 3 has functional blocks shown in Fig.2. A face area decision unit 11 verifies, from image data fed from the image processing apparatus 1, where lies the face area as a range to be compared to the template. A correlation processing unit 12 calculates the correlation between the face area verified by the face area decision unit 11 and the template previously stored in the memory device 4. A classification unit 13 performs classification based on the correlation calculated by the

correlation processing unit 12, whilst an angle prediction unit 12 performs the processing of estimating the angle of the face orientation of the object inputted from the image processing apparatus 1 in association with the classification achieved by the classification unit 13.

Referring to the flowchart of Fig.3, the operation of the above-described image processing apparatus is explained. First, at step S1, the processing of preparing a database in which the image data are linked to orientation data is executed. That is, at step S1, the face of a human being, as an object, oriented in a pre-set direction, is imaged. The image data, obtained from the image processing apparatus 1, is A/D converted by the A/D converter 2 and sent to the processing device 3. From the input image data, the processing device 3 extracts a range of a frame manually specified by the user, here a range of a rectangle including both eyes and a nose, and sends the extracted range to the memory device 4 for storing. At this time, the processing device 3 stores the angle of orientation of the face as orientation data in a linked relation to the image data. Similar processing is carried out plural times for a sole face as the face is oriented in plural different directions. This processing is carried out for plural persons so that respective image data linked with the orientation data are stored in the memory device 4. So, image data made up of a pre-set number of templates shown for example in Fig.4 are stored in the memory device 4. Although only 16 templates are shown in Fig.4 for simplicity, 130 templates, for example, are registered.

Then, at step S2, the processing of preparing images of three representative

faces is executed at step S2. This processing is shown in detail in Fig.5.

At step S11, the user specifies the positions of both eyes and the noses of 130 templates prepared at step S1. At step S12, the processing device 3 extracts an image of a pre-set size from each template so that the center of gravity of an area specified by the three points of both eyes and the nose, designated at step S11, will be at the center of the image. At step S13, the user classifies the images, extractd at step S12 from the respective templates, into three face classes, by a manual operation, depending on the face orientation. For example, an image looking on the front side, an image on the right side of the face and an image on the left side of the face are classified into a first face class, a second face class and a third face class, respectively.

Then, at step S14, the processing device 3 prepares an image of a representative face by calculating a mean value of the images in the three face classes. Since the effective area differs with face orientation, as shown in Fig.4, the templates classified into respective face classes are not necessarily the same. So, the image averaging processing is carried out by registering the eye positions under the templates of the different shapes.

If there are templates with respective different effective areas, as shown in Figs.6A to 6C, the averaging is carried out within a range of the smallest area A. From the image data  $D_A$  of the smallest area A, the image data  $D_B$  of the area B and from the image data  $D_C$  of the area C, an average value  $R_{AVG}$ , shown by

$$R_{AVG} = (D_A + D_B + D_C)/3$$

is calculated as image data of the representative face of the representative faces.

Alternatively, referring to Fig.8, an average value  $R_{AVG}$  is calculated from the three templates (areas A, B and C), within a range of the smallest area A, by an equation:

$$R_{AVG1} = (D_A + D_B + D_C)/3$$

to obtain image data of the representative face. Within a range B outside the range A, an average value  $R_{AVG2}$  is calculated from the two templates (areas B and C) by an equation:

$$R_{AVG2} = (D_B + D_C)/2$$

to obtain image data of the representative face. In a range C outside the range B, the image data  $D_C$  is the image data of the representative face. In this case, the number of the areas for averaging is changed from area to area.

If an average value is taken of the areas A, B and C, calculations are not made on the assumption that the pixels outside the area A and those outside the area B are not assumed to be 0, but it is assumed that there exists a pre-set value K. Thus, as shown in Fig.9, an average value  $R_{AVG2}$ , shown by the equation:

$$R_{AVG2} = (K + D_B + D_C)/3$$

is calculated within the area B outside the area A to give image data of the representative face, whereas, within the area C outside the area B, an average value  $R_{AVG3}$ , shown by the equation:

$$R_{AVG3} = (2K + D_C)/3$$

is calculated to give image data of the representative face.

In finding an average value of the respective areas A to C, it is also possible to calculate an average value  $R_{AVG4}$ , shown by the equation:

$$R_{AVG4} = (K + D_B + D_C)/n$$

where a parameter n is the number of the face classes, to give image data of the representative face.

The program then moves to step S15 where it is verified whether or not the processing on the 130 templates in their entirety has come to a close. If the processing has not come to a close, the program moves to step S16 where it is verified whether or not the calculations of the correlative value C for the images of the entire representative faces have come to a close. If the calculations of the correlative value C with the images of the three representative faces have not come to a close, the program moves to step S17 where the processing device 3 calculates the correlative value C with the image of the representative face for which the correlative value C has not been found, and stores the calculated correlative value C. The program then reverts to step S16 to repeat the processing until the processing of step S17 has verified that the correlative values C with the images of the three representative faces with the sole template are verified to have been found at step S16.

The correlative value C is calculated in accordance with, for example, the following equation (1):

$$C = \frac{\sum_i (R_i - R_{AVG})(T_i - T_{AVG})}{\sqrt{\sum_i (R_i - R_{AVG})^2 \sum_i (T_i - T_{AVG})^2}} \quad \dots(1)$$

where R denotes the image data of the representative face and  $R_{AVG}$  its average value, T denotes image data of a template and  $T_{AVG}$  denotes its average value.

If calculations of the correlative value C between a sole template and the images of the three representative faces come to a close, the program moves to step S18 where the processing device 3 classifies the template to the face class, to which belongs the image of the representative face having the highest correlation among the correlative values C with the images of the three representative faces.

The program then reverts to step S15 where it is checked whether or not the same processing has been performed on the 130 templates in their entirety. When the similar processing comes to a close for the 130 templates in their entirety, the program moves to step S19 where the processing device 3 checks whether or not the number of templates among the 130 templates in which the belonging face classes have been changed to past face classes has become smaller than a pre-set threshold value. If the result of decision at this step S19 is NO, the program reverts to step S14, where a pixel-based average value of an image of the template belonging to the class is calculated for each face class to prepare (update) an image of the representative face. For the newly prepared images of the three representative faces, the processing of

steps S15 to S18 is executed to calculate the correlative values between the 130 templates and the new images of the three representative faces. Each template has its face class changed so that the face class is now the image of the representative face, among the images of the representative faces, which has closer correlative values.

The program moves to step S19 where it is checked whether or not the number of the templates, the face classes of which have been changed, is smaller than a pre-set threshold value. If the number of the templates, the face classes of which have been changed, is verified to be not smaller than the threshold value, the program reverts to step S14 to execute the subsequent processing repeatedly. If the number of the templates is verified to be equal to or smaller than the threshold value, the processing comes to a close. At this step, convergence check may also be carried out, using the rate of change of the number of the templates, the face classes of which have been changed, or the number of times of the re-classification processing operations, as a threshold value.

An average face of the three face classes, shown for example in Fig.10, is registered as the image of the representative face of each face class, in the manner as described above.

Fig.11 schematically shows the relation of the representative faces of the three face classes and the templates belonging to the face classes. In this figure, the representative face 1 of the class 1 is an average face of the templates 1-1 to 1-p, the representative face 2 of the class 2 is an average face of the templates 2-1 to 2-q, and

the representative face 3 of the class 3 is an average face of the templates 3-1 to 3-r.

In the present example, the value of  $p+q+r$  is 130.

In the present example, the pixel-based average value of the image of the template belonging to a face class is calculated from one face class to another to prepare an image of the representative face of each face class. Besides the above-mentioned average value, the image of the representative face of each face class may also be prepared using a pixel value having a median value of the entire pixels, a median value between the maximum and minimum values or the pixel value having an intermediate value, in place of the above-mentioned average value.

It is noted that, if, in the processing of preparing the images of the three representative faces from the 130 templates prepared at step S1, the information on the angle of orientation of respective faces are previously imparted to the 130 templates, it is possible to perform the processing of initially classifying the images of the respective templates to the above-mentioned first to third face classes, at step S10, based on the above-mentioned angular information, in place of the processing at steps S11 to S13, as shown in Fig.12. That is, the images of the respective templates are classified into face classes of the representative faces N, based on the angular information  $X_0$  to  $X_n$ , as shown in Fig.13.

After the images of a number, herein three, of the representative faces, smaller than the number of the templates in the database, herein 130, have been prepared as described above, the processing of detecting the orientation of the faces to the really

inputted image is executed. That is, at step S3 of Fig.3, the face of the object is imaged at step S3 of Fig.3, by the image processing apparatus 1. The processing device 3 executes face position decision processing and face angle decision processing, at steps S4 and S5, respectively. The face position decision processing of step S4 is shown in detail in the flowchart of Fig.14.

First, at step S31, the face area decision unit 11 of the processing device 3 verifies whether or not the processing for the images of the three representative faces in their entirety has come to a close. If the processing has not come to a close, the program moves to step S32 to set an image of a representative face to be processed next. At step S33, the face area decision unit 11 checks whether or not the searching of the entire area of the image of the representative face set at step S32 has come to a close. If this searching has not come to a close, the program moves to step S34 where the face area decision unit 11 calculates the correlative value between the image of an area of the same size as that of the template, referenced to a pixel under consideration in a frame of an input image and the image of the targeted representative face.

If, for example, a center image of the images of the three representative faces shown in Fig.10 is selected as a representative face being processed, the areas of the same size as this representative face are sequentially extracted, beginning from the upper left area of the frame of the input image, to calculate the correlation between the image of the area and the image of the representative face.

The program then moves to step S35 where it is checked whether or not the correlative value as found by the calculations at step S34 is larger than the maximum value MAX of the correlative value held at the time point. If the result of decision at this step S35 is YES, the program moves to step S36 to store the correlative value as found by the calculations at step S34 as the maximum value MAX at the time point.

The program then reverts to step S33 where it is checked whether or not the search has been performed over the entire area. If the search is not performed over the entire area, the program moves to step S34 where the face area decision unit 11 moves the position of the area corresponding to the representative face pixel-by-pixel within the frame of the input image as from the previous time position. The correlative value between the image of the area of the new position and the image of the representative face is again calculated. At step S35, it is checked whether or not the correlative value as found at step S34 is larger than the maximum value MAX stored in the past at step S36. If the result of decision at this step S35 is YES, that is if the correlative value as found at step S34 is larger than the maximum value M stored in the past at step S36, the maximum value MAX is updated at step S36 with the correlative value as found at step S34. If it is found at step S35 that the maximum value MAX is smaller than the correlative value as found at step S34, the processing at step S36 is skipped.

The above-described processing is repeatedly carried out by sequentially moving (searching) the area in the frame of the input image to be compared to the representative face from upper left to lower left. This processing is repeatedly carried

out until it is verified at step S33 that searching has been carried out over the entire area of the input image.

If, at step S33, it is verified that searching has come to a close over the entire area of the frame of the input image, the program moves to step S37 where the correlation processing unit 12 stores the position for which the maximum correlative value in a frame of an input image has been obtained and the maximum correlative value, that is the maximum value MAX obtained by the processing of step S36.

Fig.16 shows an example of the position for which the maximum correlative value has been obtained. That is, a rectangular frame in Fig.16 represents the range of an area corresponding to the representative face, with its upper left corner being a position of the representative face. Fig.16 shows the correlative values, obtained as a result of searching, in terms of concentration, with the higher and lower correlative values being indicated so as to be whiter and blacker, respectively. In the example of Fig.16, the vicinity of the upper left portion of the displayed frame is shown in white, with the other areas being shown in black. Therefore, in the example of Fig.16, the position for which an image having the highest correlation to the representative face shown on the upper left of the screen is the position shown by the frame. Meanwhile, Fig.17 shows the high correlative value area to an enlarged scale to indicate the correlative values three-dimensionally.

The program then reverts to step S31 to check whether or not the processing of the images of the three representative faces has come to a close. In the present

example, since the processing on only one image of the representative face has come to a close, the right-side image, among the images of the three representative faces shown in Fig.10, is selected as being a representative face to be processed in the processing at step S33 ff.

As a result, the maximum correlative value between the input image shown in Fig.15B and the image of the representative face shown on the right side of Fig.10, and the position for which the maximum correlative value has been obtained, are found, with the corresponding value being stored at step S37.

The program then reverts to step S31 where the image of the representative face shown on the left of Fig.10 is selected as a targeted representative face, and the position for which the maximum correlative value between the image and the input image shown in Fig.15B, as well as the correlative value, is obtained, is retrieved and saved at step S37.

If the processing for the images of the three representative faces has come to a close, as described above, the check of step S31 is carried out, after which the program moves to step S38 where the correlation processing unit 12 stores the position of the image having the maximum correlative value with the input image, among the images of the three representative faces, as the face position of the input image.

In the present example, the input image is an image of a face looking forwards, as shown in Fig.15B, so that the correlation with the center image, among the images of the three representative faces shown in Fig.10, is maximum. So, the position shown

by the white frame is stored as the maximum position of the correlation of this input image.

When the face position of the input image (position of a range to be compared to the images of the three representative faces) is specified as described above, the face angle decision processing of step S5 of Fig.3 is carried out. The face angle decision processing is shown in detail in the flowchart of Fig.18.

First, at step S51, the correlation processing unit 12 verifies whether or not the processing for calculating the correlative values between the images of the three representative faces and the area of the input image shown in a frame in Fig.15B has come to a close.

If the processing has not come to a close, the program moves to step S52 to set an image of the representative face to be processed next. At step S53, the correlation processing unit 12 performs the processing of calculating the correlation between the image of the area represented by the frame in Fig.15B and the image of the representative face set at step S53, for example, the image of the representative face shown centrally in Fig.10. The so-calculated correlative value is stored at step S54. Meanwhile, since this correlative value is the same as the value stored for the image of the representative face at step S37 of Fig.14, the processing of steps S53 and S54 in the image of the representative face can be omitted, if so desired.

The program then reverts to step S51 to execute at step S53 the calculations of finding out the correlative value between the image of the representative face shown

on the right side of Fig.10 and the area shown in the frame of Fig.15B. The so-calculated correlative value C is stored at step S54. Although the calculations of the correlative value between the image of the representative face and the input image shown in Fig.15B are already executed at steps S33 to S36 in Fig.14, the value stored at step S37 is not necessarily the result of comparison with respect to the area shown in the frame of Fig.15B (the area which gives the maximum correlation with respect to the image of the representative face shown centrally in Fig.10), the correlative value is actually carried out and newly stored insofar as the image of this representative face is concerned.

In similar manner, the processing of steps S53 and S54 is executed for the representative face shown on the left side of Fig.10 so that the correlative value with respect to the area shown framed in Fig.15B is calculated and stored.

When the correlative value between the pre-set area of the input image and the images of the three representative faces is found as described above, the classification unit 13 executes classification processing based on the correlative value with respect to the images of the representative faces.

When the classification unit 13 has determined the class based on the correlative value, it outputs the class to an angle estimation unit 14. It is noted that the class is uniquely determined, given the correlative values C1, C2 and C3, for example. Specifically, the class means such a class used in a technique of classifying input data based on similarity of properties and of applying data processing as found by learning

at the outset from one relevant class to another.

The angle estimation unit 14 at step S56 calculates the angle  $\hat{\theta}$  of the input image in accordance with the following equation:

$$\hat{\theta} = w1C1 + w2C2 + w3C3 \quad \dots(2)$$

wherein C1 to C3 represent the correlative value of the input image to the images of the three representative faces stored at step S54 and w1 to w3 are coefficients. The angle estimation unit 14 memorizes these coefficients w1 to w3 from one class determined based on the correlative value to another. Specifically, the angle estimation unit 14 at step S56 reads out coefficient sets corresponding to the classes inputted from the classification unit 13 and multiplies the coefficient sets with the correlative values C1 to C3, inputted from the correlation processing unit 12 through the classification unit 13, to calculate the angle  $\hat{\theta}$  in accordance with the equation (2).

Fig.19 shows the relation between the correlative value and the angle of orientation of the object. In Fig.19, the ordinate and the abscissa denote the correlative value and the actual angle of orientation of the object. Moreover, in Fig.19, leftward, front or rightward denote that the correlative values with respect to the input image are obtained using the images of the representative faces shown on the left, center or on the right of Fig.10. As may be seen from Fig.19, if the correlative value with respect to the input image of the object is found using the image of the representative faces facing to the front side, the highest correlative value is obtained

when the object faces to the front side, with the correlative value becoming smaller the more the object faces rightwards or leftwards.

It may be seen that, if the image of the representative face facing to the left is used, there is obtained a correlative value approximately proportionate to the angle of object orientation when the object is facing to the left from the front side. It may similarly be seen that, if the image of the representative face facing to the right is used, there is obtained a correlative value approximately proportionate to the angle of object orientation when the object is facing to the right from the front side.

Thus, if the input image is an image corresponding to the right side face of the object, as shown in Fig.20, the maximum correlative value is obtained when the input image is the image of the representative face shown on the right side of the images of the three representative faces shown in Fig.10. Similarly, if the input image is an image corresponding to the left side face of the object, as shown in Fig.21, the maximum correlative value is obtained when the input image is the left side image of the images of the three representative faces shown in Fig.10.

Meanwhile, in the learning of the class-based coefficient set, algorithms used in e.g., vector quantization, such as a k-means method, can be used to generate images of a smaller number of classes, from a large number of input images, to learn the coefficient set which will give correct results. Meanwhile, the k-means method, also termed an LBG algorithm, is disclosed in detail e.g., in "Image Information Compression", published by OHM Co. Ltd., pages 127 to 130.

The above-described principle of the present invention is shown schematically in Fig.22, from which it may be seen that, according to the present invention, a smaller number of, herein five, images of the representative faces are prepared from a large number of templates. The orientation of the input image is calculated by class classification adaptive processing for the correlative value  $C$  of an input image and an image of the representative face.

It is noted that the class classification processing is carried out by evaluating the correlative value between the image of the representative face and the input image in accordance with the sequence of operations shown in the flowchart of Fig.23.

That is, in the class classification processing, shown in the flowchart of Fig.23, it is first verified at step S71 whether or not the correlative value has been evaluated of the input image with the images of the representative faces in their entirety. If there is any image of the representative face, not evaluated, the program moves to step S72 to calculate the correlation between the image of the representative face and the input image to save the correlative value  $C$ . At step S73, the image of the next representative face is specified. The program then reverts to step S71 to repeat the processing as from step S71 up to step S73. If the evaluation has been made of the correlative values  $C1$  to  $C3$  with the images of the representative faces in their entirety, the program moves to step S74 to classify the image data in the image class of the representative face having the highest correlation.

If there are many sets (vectors) of the correlative values between the input

images with a known angle  $\theta$  and images of the representative faces, the class classification processing may be executed in accordance with the operational sequence shown in the flowchart of Fig.24.

That is, in the class classification processing, shown in the flowchart of Fig.24, the correlative values  $c1$ ,  $c2$  and  $c3$  for the images of the respective representative faces are represented at step S81 in vector, from one template to another. At step S82, the user sets initial values of the correlation vector representing the class to give representative vectors (C1 to Computer unit 3).

At step S83, it is verified whether or not the processing has been performed on the entire vectors. If there is any template to be processed, the program moves to step S84.

At step S84, it is verified whether or not the processing has been performed on the representative vectors in their entirety. If there is any representative vector to be processed, the program moves to step S85 to effect distance evaluation such as inner product calculations of the correlation vector and the representative vectors. The program then reverts to step S84 to repeat the steps S84 and S85 to effect distance evaluation with the representative vectors for the entire correlation vectors. The program then reverts to step S86.

At step S86, classification is made into a class to which belongs the representative vector having the shortest vector-to-vector distance, that is having the high correlation and high similarity. The program then reverts to step S83 to repeat

the processing from step S83 to step S86 to effect classification into classes for the correlation vectors in their entirety. The program then moves to step S87.

At step S87, the average value is calculated in the same class to find new representative vectors C1' to C3'.

At the next step S88, distance evaluation, exemplified by inner product calculation, is performed between the newly found representative vectors C1' to C3' and the original representative vectors C1 to C3. If the change in the representative vector is below a certain value, the program moves to step S89 to determine this representative vector as answer to terminate the processing.

The class-based coefficient set learning processing is carried out by classifying the total learning data into classes, and by learning the coefficient set for the data of the same class by the least square method, in accordance with, for example, the sequence of the flowchart of Fig.25.

That is, in the class-based coefficient set learning processing, it is first verified at step S91 for all of classes. If there is any class to be processed, the program moves to step S92 where it is checked whether or not all of data in the class being processed have been processed. If there is any data to be processed, the program moves to step S93.

At step S93, teacher data (angle  $\hat{\theta}$ ) is read in and introduced into a normalization equation. At the next step S94, the representative vectors C1 to C3 are read in and introduced into a normalization equation. The program then reverts to step

S92 to repeat the processing of from step S92 to step S94 to generate the normalization equation for the entire data in the class being processed. The program then moves to step S95.

At step S95, the normalization equation is solved by the least square method to determine the coefficient set w1 to w3 of the class under consideration.

At the next step S96, the next class is designated. The program then reverts to step S91 to repeat the processing from step S91 to step S96 to determine the coefficient set w1 to w3 for all of the sets. This completes the learning processing.

Although the object in the above processing is a human face, the present invention can be applied to detection of orientation of an object other than the human being. The distance between the images can be measured by a method other than the correlation method.

As the processing device 3 for performing the above-described processing, a routine computer system 310, made up of a CPU (central processing unit) 312, a memory 313, an input interface 314, a user interface 315 and an output interface 316, interconnected over a bus 311, is used. What is furnished to a user is a recording medium having recorded thereon a computer-controllable program adapted for realizing the functions of the processing device 3, that is an image processing program adapted for executing image processing in accordance with the flowchart shown in Fig.3. The image processing program includes, for example, a representative face preparing program, for preparing a representative face in accordance with the

flowcharts shown in Figs.5 and 12, a face position decision program for effecting face position decision processing in accordance with the flowchart of Fig.14, and a face angle decision program for effecting face angle decision processing in accordance with the flowchart of Fig.18. The image processing program also includes a class classification processing program for effecting classification into classes in accordance with the flowcharts of Figs.23 and 24, and a learning processing program for effecting learning processing of coefficient sets in accordance with the flowchart of Fig.25. The recording medium may be exemplified by a transmission medium over networks, such as the Internet or the digital satellite, in addition to the information recording mediums, such as magnetic disc or CD-ROM.

According to the present invention, in which the groups of the input image data is determined, based on the smaller number of the images of the representative faces, prepared from plural templates, and on the distance from the input image data, and the angle of the input image is calculated based on the so-determined group, the object angle can be found readily and quickly.

That is, in a representative sample generating method for generating representative sample data of a plurality of groups, based on a plurality of sample data initially classified into the plural groups, group feature data representing feature of sample data are detected in each of the groups, the distances between all of the sample data and the group feature data of each group are detected, all of the sample data are re-classified into the plural groups based on the distances, and the group feature data

detection and the re-classification are repeated until the number of the sample data classified into groups different from the previous group is converged by the re-classification. It is therefore possible to change the images of the representative samples, for example, the representative faces, as time elapses, such that an optimum representative face can be prepared automatically with lapse of time. When desired to obtain an image of a pre-fixed representative face, an image of the optimum representative face can be found automatically.

According to the present invention, adaptive grouping is possible, with the grouping criterium being changed on-line, so that changes in the population can be coped with flexibly. The learning function is imparted by the recursive structure to realize the optimum classification technique automatically.

In the sample feature data generating method according to the present invention, the distance between input sample data and each representative sample data generated previously for each of a plurality of groups are detected, the input sample data are classified into one of the classes, based on the distances of the input sample data from representative sample data of the plural groups, and sample feature data representing the feature of the input sample data are generated in accordance with a system pre-set for each class. That is, according to the present invention, linear prediction values are not used directly, but are used as parameters, and are associated with the actually sensed values, so that, if non-linear elements are mixed into e.g., the same class, learning by the linear prediction equation is possible on the condition that the non-

linear elements can be converted into linear elements using e.g., a linear-non-linear conversion table, thereby reducing the influence of the non-linear elements.

Moreover, according to the present invention, linear prediction values are not used directly, but are used as parameters, and are associated with the actually sensed values, so that, if non-linear elements are mixed into e.g., the same class, the influence of the non-linear elements can be absorbed using e.g. the linear-non-linear conversion table.

## Claims

1. A representative sample generating apparatus for generating representative sample data of each of a plurality of groups, based on a plurality of sample data initially classified into said plural groups, said apparatus comprising:

group feature data detection means for detecting group feature data representing feature of sample data in each of said groups,

distance detection means for detecting the distances between all of the sample data and the group feature data of each group;

re-classification means for re-classifying all of said sample data into said plural groups based on said distances;

convergence detection means for detecting whether or not the number of sample data classified into groups different from previous groups is converged as a result of re-classification by said re-classification means; and

decision means for repeating the processing by said group feature data detection means, re-classification means and said convergence detection means until said convergence detection means has detected convergence, and for determining the group feature data of each group prevailing at the time of said convergence as detected by said convergence detection means as representative sample data of each group.

2. The representative sample generating apparatus according to claim 1

wherein

said group feature data detection means detects an average value of sample data

in each group as said group feature data.

3. The representative sample generating apparatus according to claim 1

wherein

    said convergence detection means detects convergence when the number of sample data classified into a group different from the previous group is equal to or smaller than a pre-set number.

4. The representative sample generating apparatus according to claim 1

wherein

    said distance detection means detects the distance by calculating the correlation of the group feature data of each group with respect to all of sample data.

5. The representative sample generating apparatus according to claim 1

wherein

    said sample data is image data.

6. The representative sample generating apparatus according to claim 5

wherein

    said group feature data detection means generates group feature data according to the orientation of an image represented by image data.

7. A representative sample generating method for generating representative sample data of each of a plurality of groups, based on a plurality of sample data initially classified into said plural groups, said method comprising:

    a step of detecting group feature data representing feature of sample data in

each of said groups,

a step of detecting the distances between all of the sample data and the group feature data of each group;

a step of re-classifying all of said sample data into said plural groups based on said distances;

a step of detecting whether or not the number of sample data classified into groups different from previous groups is converged as a result of re-classification by said re-classification step; and

a step of repeating the processing by said group feature data detection step, re-classification step and said convergence detection step until said convergence detection step has detected convergence, and for determining the group feature data of each group prevailing at the time of said convergence as detected by said convergence detection step as representative sample data of each group.

8. A recording medium having recorded thereon a computer-controllable program for generating representative sample data of each of a plurality of groups, based on a plurality of sample data initially classified into said plural groups, said program comprising:

a step of detecting group feature data representing feature of sample data in each of said groups,

a step of detecting the distances between all of the sample data and the group feature data of each group;

a step of re-classifying all of said sample data into said plural groups based on said distances;

a step of detecting whether or not the number of sample data classified into groups different from previous groups is converged as a result of re-classification by said re-classification step; and

a step of repeating the processing by said group feature data detection step, reclassification step and said convergence detection step until said convergence detection step has detected convergence, and for determining the group feature data of each group prevailing at the time of said convergence as detected by said convergence detection step as representative sample data of each group.

9. A representative sample generating apparatus for generating representative sample data of each of a plurality of groups by classifying said plural sample data, having appended supplementary data indicating respective feature, into said plural groups, said apparatus comprising:

initial classification means for initially classifying said plural sample data into plural groups, based on said supplementary data;

group feature data detection means for detecting group feature data representing feature of said sample data in each of said groups;

distance detection means for detecting the distances between all of the sample data and the group feature data of each group;

re-classification means for re-classifying all of said sample data into said plural

groups based on said distances;

convergence detection means for detecting whether or not the number of sample data classified into groups different from previous groups is converged as a result of re-classification by said re-classification means; and

decision means for repeating the processing by said group feature data detection means, said re-classification means and the convergence detection means until said convergence detection means has detected convergence, and for determining the group feature data of each group prevailing at the time of said convergence as detected by said convergence detection means as representative sample data of each group.

10. The representative sample generating apparatus according to claim 9

wherein

said group feature data detection means detects an average value of sample data in each group as said group feature data.

11. The representative sample generating apparatus according to claim 9

wherein

said convergence detection means detects convergence when the number of sample data classified into a group different from the previous group is equal to or smaller than a pre-set number.

12. A representative sample generating method for generating representative sample data of each of a plurality of groups by classifying said plural sample data, having appended supplementary data indicating respective feature, into said plural groups,

said method comprising:

a step of initially classifying said plural sample data into plural groups, based on said supplementary data;

a step of detecting group feature data representing feature of said sample data in each of said groups;

a step of detecting the distances between all of the sample data and the group feature data of each group;

a step of re-classifying all of said sample data into said plural groups based on said distances;

a step of detecting whether or not the number of sample data classified into groups different from previous groups is converged as a result of re-classification by said re-classification step; and

a step of repeating the processing by said group feature data detection step, said re-classification step and the convergence detection step until said convergence detection step has detected convergence, and of determining the group feature data of each group prevailing at the time of said convergence as detected by said convergence detection step as representative sample data of each group.

13. A recording medium having recorded thereon a computer-controllable program for generating representative sample data of each of a plurality of groups by classifying said plural sample data, having appended supplementary data indicating respective feature, into said plural groups, said program comprising:

a step of initially classifying said plural sample data into plural groups, based on said supplementary data;

a step of detecting group feature data representing feature of said sample data in each of said groups;

a step of detecting the distances between all of the sample data and the group feature data of each group;

a step of re-classifying all of said sample data into said plural groups based on said distances;

a step of detecting whether or not the number of sample data classified into groups different from previous groups is converged as a result of re-classification by said re-classification step; and

a step of repeating the processing by said group feature data detection step, said re-classification step and the convergence detection step until said convergence detection step has detected convergence, and of determining the group feature data of each group prevailing at the time of said convergence as detected by said convergence detection step as representative sample data of each group.

14. A classification apparatus for re-classifying sample data initially classified into a plurality of groups, said apparatus comprising:

group feature data detection means for detecting group feature data representing feature of the sample data for each of said groups;

distance detection means for detecting the distances between all of the sample

data and the group feature data of each group;

re-classification means for re-classifying all of said sample data into said plural groups based on said distances;

convergence detection means for detecting whether or not the number of sample data classified into groups different from previous groups is converged as a result of re-classification by said re-classification means; and

decision means for repeating the processing by said group feature data detection means, said re-classification means and the convergence detection means until said convergence detection means has detected convergence, and for determining the results of re-classification of each sample data by said re-classification means on convergence detection by said convergence detection means.

15. A classification method for re-classifying sample data initially classified into a plurality of groups, said method comprising:

a step of detecting group feature data representing feature of the sample data for each of said groups;

a step of detecting the distances between all of the sample data and the group feature data of each group;

a step of re-classifying all of said sample data into said plural groups based on said distances;

a step of detecting whether or not the number of sample data classified into groups different from previous groups is converged as a result of re-classification by

said re-classification step; and

a step of repeating the processing by said group feature data detection step, said re-classification step and the convergence detection step until said convergence detection step has detected convergence, and of determining the results of re-classification of each sample data by said re-classification step on convergence detection by said convergence detection step.

16. A recording medium having recorded thereon a computer-controllable program for performing processing of re-classifying a plurality of sample data, based on a plurality of sample data initially classified into plural groups, said program comprising:

a step of detecting group feature data representing feature of sample data in each of said groups,

a step of detecting the distances between all of the sample data and the group feature data of each group;

a step of re-classifying all of said sample data into said plural groups based on said distances;

a step of detecting whether or not the number of sample data classified into groups different from previous groups is converged as a result of re-classification by said re-classification step; and

a step of repeating the processing by said group feature data detection step, reclassification step and said convergence detection step until said convergence detection step has detected convergence, and of determining the results of re-

classification of each sample data by said re-classification step on convergence detection in said convergence detection step as ultimate results of classification of each of said groups.

17. A classification apparatus for classifying plural sample data, having appended supplementary data indicating respective feature, into plural groups, said apparatus comprising:

initial classification means for initially classifying said plural sample data into plural groups, based on said supplementary data;

group feature data detection means for detecting group feature data representing feature of said sample data in each of said groups;

distance detection means for detecting the distances between all of the sample data and the group feature data of each group;

re-classification means for re-classifying all of said sample data into said plural groups based on said distances;

convergence detection means for detecting whether or not the number of sample data classified into groups different from previous groups is converged as a result of re-classification by said re-classification means; and

decision means for repeating the processing by said group feature data detection means, said re-classification means and the convergence detection means until said convergence detection means has detected convergence, and for determining the results of re-classification of each sample data by said re-classification means on

convergence detection in said convergence detection step as ultimate results of classification of each of said groups.

18. A classification method for classifying plural sample data, having appended supplementary data indicating respective feature, into plural groups, said method comprising:

a step of initially classifying said plural sample data into plural groups, based on said supplementary data;

a step of detecting group feature data representing feature of said sample data in each of said groups;

a step of detecting the distances between all of the sample data and the group feature data of each group;

a step of re-classifying all of said sample data into said plural groups based on said distances;

a step of detecting whether or not the number of sample data classified into groups different from previous groups is converged as a result of re-classification by said re-classification step; and

a step of repeating the processing by said group feature data detection step, said re-classification step and the convergence detection step until said convergence detection step has detected convergence, and of determining the results of re-classification of each sample data by said re-classification step on convergence detection in said convergence detection step as ultimate results of classification of

each of said groups.

19. A recording medium having recorded thereon a computer-controllable program for classifying plural sample data, having appended supplementary data indicating respective feature, into plural groups, said program comprising:

a step of initially classifying said plural sample data into plural groups, based on said supplementary data;

a step of detecting group feature data representing feature of said sample data in each of said groups;

a step of detecting the distances between all of the sample data and the group feature data of each group;

a step of re-classifying all of said sample data into said plural groups based on said distances;

a step of detecting whether or not the number of sample data classified into groups different from previous groups is converged as a result of re-classification by said re-classification step; and

a step of repeating the processing by said group feature data detection step, said re-classification step and the convergence detection step until said convergence detection step has detected convergence, and of determining the results of re-classification of each sample data by said re-classification step on convergence detection in said convergence detection step as ultimate results of classification of each of said groups.

20. A coefficient data generating apparatus for generating a coefficient data set adapted for generating sample feature data from new sample data not having sample feature data, based on a database in which there are pre-stored said sample feature data and sample data associated with said sample feature data, said apparatus comprising:

classification means for classifying said sample data into a plurality of classes, based on the relation thereof with representative sample data which is set to each classification and which is associated with the sample feature data;

means for generating, for each class, a normal equation having the values of the sample feature data and the sample data as previously known data and having coefficient data as unknown data; and

coefficient data generating means for solving said normal equation for each class to generate said coefficient data set for each class.

21. A coefficient data generating method for generating a coefficient data set adapted for generating sample feature data from new sample data not having sample feature data, based on a database in which there are pre-stored said sample feature data and sample data associated with said sample feature data, said method comprising:

a step of classifying said sample data into a plurality of classes, based on the relation thereof with representative sample data which is set to each classification and which is associated with the sample feature data;

a step of generating, for each class, a normal equation having the values of the sample feature data and the sample data as previously known data and having

coefficient data as unknown data; and

a step of solving said normal equation for each class to generate said coefficient data set for each class.

22. A recording medium having recorded thereon a computer-controllable program adapted for generating a coefficient data set adapted for generating sample feature data from new sample data not having sample feature data, based on a database in which there are pre-stored said sample feature data and sample data associated with said sample feature data, said program comprising:

a step of classifying said sample data into a plurality of classes, based on the relation thereof with representative sample data which is set to each classification and which is associated with the sample feature data;

a step of generating, for each class, a normal equation having the values of the sample feature data and the sample data as previously known data and having coefficient data as unknown data; and

a step of solving said normal equation for each class to generate said coefficient data set for each class.

23. A sample feature data generating apparatus comprising:

distance detection means for detecting distance between input sample data and each representative sample data generated previously for each of a plurality of groups;

classification means for classifying said input sample data into one of said classes, based on the distances of said input sample data from representative sample

data of said plural groups; and

sample feature data generating means for generating sample feature data representing the feature of said input sample data in accordance with a system pre-set for each class.

24. The sample feature data generating apparatus according to claim 23

wherein

said sample feature data generating means includes

storage means for storing a coefficient data set pre-set for each class;

prediction equation generation generating means for generating a prediction equation based on the coefficient data set read out from said storage means based on a class determined by said classification means; and

data generating means for solving said prediction equation to generate said sample feature data.

25. The sample feature data generating apparatus according to claim 23

wherein

said sample feature data generating means generates sample feature data having consecutive values on a line interconnecting said plural representative sample data.

26. The sample feature data generating apparatus according to claim 23

wherein

said distance detection means detects a distance by calculating the correlation between input sample data and representative sample data generated at the outset for

each of said groups.

27. The sample feature data generating apparatus according to claim 23

wherein

said input sample data is image data.

28. The sample feature data generating apparatus according to claim 27

wherein

said sample feature data generating means generates sample feature data according to the orientation of an image represented by image data.

29. A sample feature data generating method comprising:

a step of detecting distance between input sample data and each representative sample data generated previously for each of a plurality of groups;

a step of classifying said input sample data into one of said classes, based on the distances of said input sample data from representative sample data of said plural groups; and

a step of generating sample feature data representing the feature of said input sample data in accordance with a system pre-set for each class.

30. A recording medium having recorded thereon a computer-controllable program adapted for generating sample feature data representing feature of input sample data, said program comprising:

a step of detecting distance between input sample data and each representative sample data generated previously for each of a plurality of groups;

a step of classifying said input sample data into one of said classes, based on the distances of said input sample data from representative sample data of said plural groups; and

a step of generating sample feature data representing the feature of said input sample data in accordance with a system pre-set for each class.

31. A data processing apparatus comprising:

a representative sample generating device adapted for repeatedly performing the operations of detecting group feature data based on a plurality of sample data initially classified into a plurality of groups, said group feature data representing feature of sample data in each of said groups, detecting distances between all of the sample data and the group feature data of each group, re-classifying all of said sample data into said plural groups, based on the detected distance, and detecting whether or not the number of sample data classified into groups different from the previous groups has converged, and for determining the group feature data of each group prevailing on detection of the convergence by said re-classification of the number of sample data classified into groups different from the previous group, as representative sample data of each group; and

a sample feature data generating device adapted for detecting the distances of input sample data to representative sample data of each group, classifying said input sample data into one of a plurality of classes, based on the distances of said input sample data to the representative sample data of each group, and for generating sample

feature data representing feature of said input sample data in accordance with a system pre-set for each class.

**32. A data processing method comprising:**

a representative sample data determining step of repeatedly performing the operations of detecting group feature data based on a plurality of sample data initially classified into a plurality of groups, said group feature data representing feature of sample data in each of said groups, detecting distances between all of the sample data and the group feature data of each group, re-classifying all of said sample data into said plural groups, based on the detected distance, and detecting whether or not the number of sample data classified into groups different from the previous groups has converged, and for determining the group feature data of each group prevailing on detection of the convergence by said re-classification of the number of sample data classified into groups different from the previous group, as representative sample data of each group; and

a sample feature data generating step of detecting the distances of input sample data to representative sample data of each group, classifying said input sample data into one of a plurality of classes, based on the distances of said input sample data to the representative sample data of each group, and for generating sample feature data representing feature of said input sample data in accordance with a system pre-set for each class.

**33. A recording medium having recorded thereon a computer-controllable program**

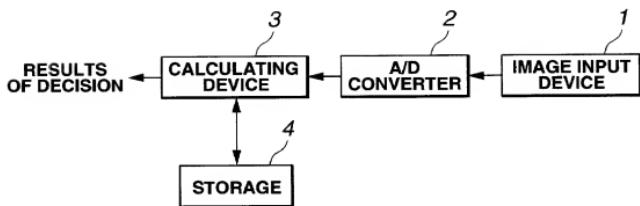
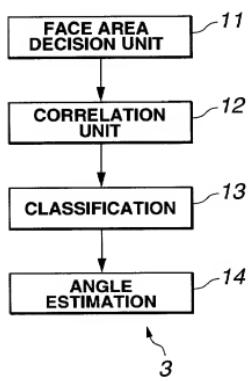
adapted for performing the processing of generating sample feature data representing feature of input sample data, said program comprising:

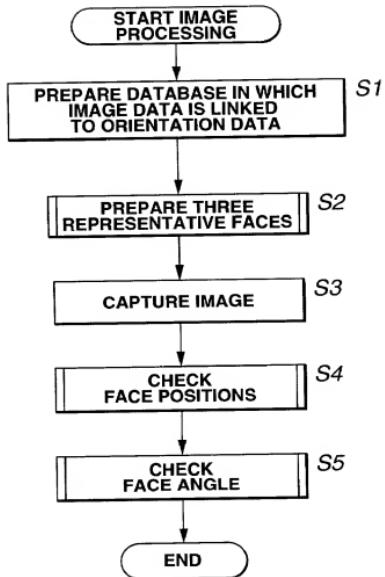
a representative sample data determining step of repeatedly performing the operations of detecting group feature data based on a plurality of sample data initially classified into a plurality of groups, said group feature data representing feature of sample data in each of said groups, detecting distances between all of the sample data and the group feature data of each group, re-classifying all of said sample data into said plural groups, based on the detected distance, and detecting whether or not the number of sample data classified into groups different from the previous groups has converged, and determining the group feature data of each group prevailing on detection of the convergence by said re-classification of the number of sample data classified into groups different from the previous group, as representative sample data of each group; and

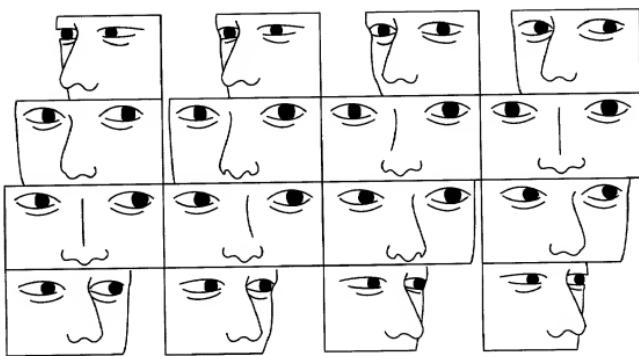
a sample feature data generating step of detecting the distances of input sample data to representative sample data of each group, classifying said input sample data into one of a plurality of classes, based on the distances of said input sample data to the representative sample data of each group, and of generating sample feature data representing feature of said input sample data in accordance with a system pre-set for each class.

## ABSTRACT

A group of input image data is determined based on the distance between images of a number of representative faces, prepared from plural templates, and the input image data (correlative values C1 to C5). The number of representative faces is smaller than the number of the templates. An angle of the input image is calculated based on the so-determined group.

**FIG.1****FIG.2**

**FIG.3**



**FIG.4**

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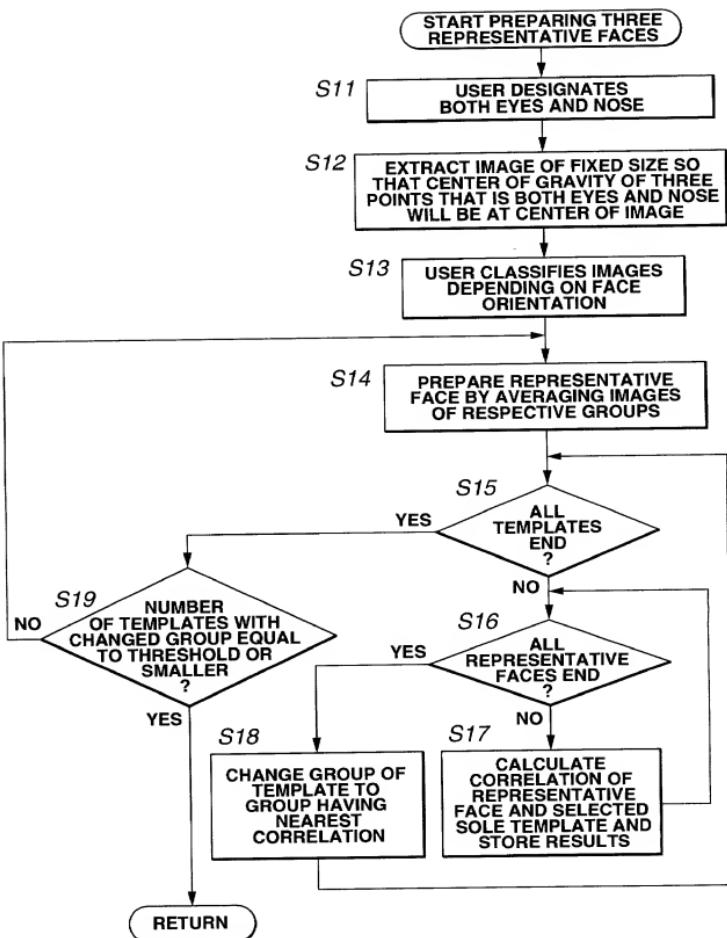
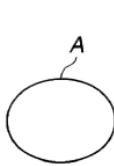
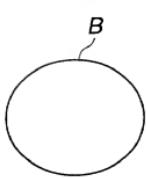
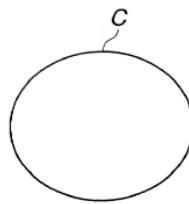
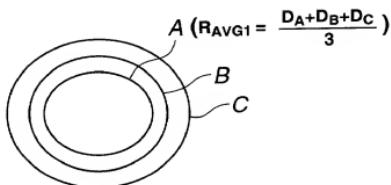
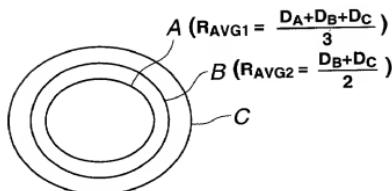
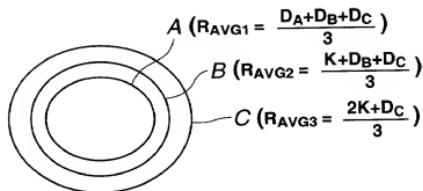


FIG.5

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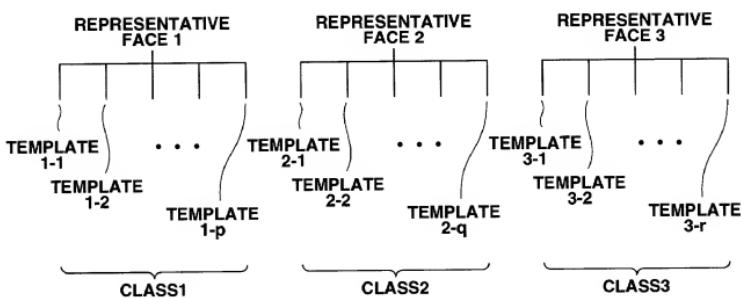
**FIG.6A****FIG.6B****FIG.6C****FIG.7****FIG.8****FIG.9**

$$A (R_{AVG1} = \frac{D_A+D_B+D_C}{3})$$

$$B (R_{AVG2} = \frac{D_B+D_C}{2})$$

$$C (R_{AVG3} = \frac{2K+D_C}{3})$$

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**FIG.10****FIG.11**

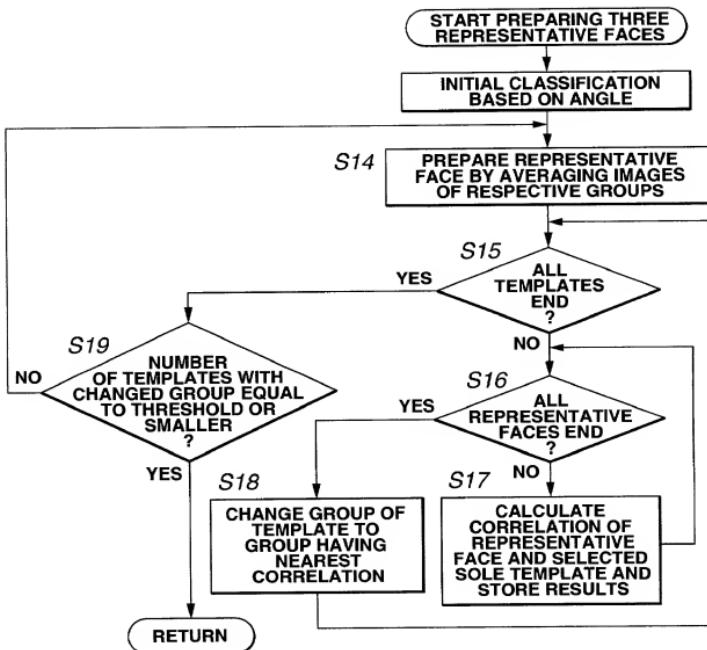
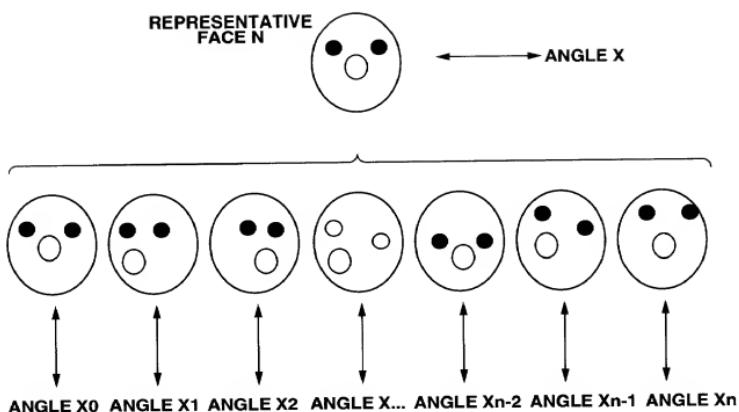


FIG.12



**FIG.13**

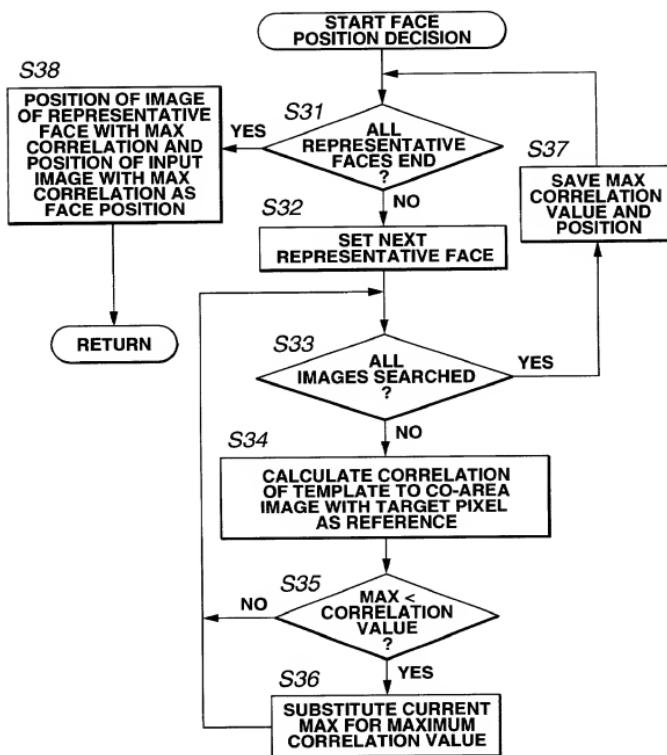
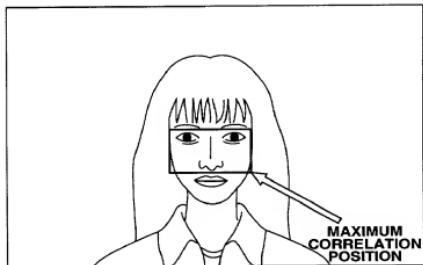
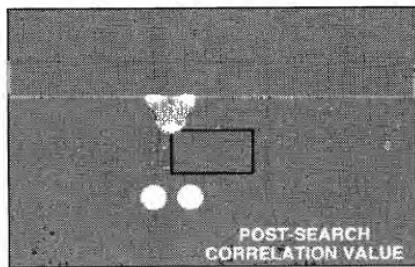


FIG.14

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**FIG.15A****FIG.15B**

09/700168 - FIG.15A

**FIG.16**

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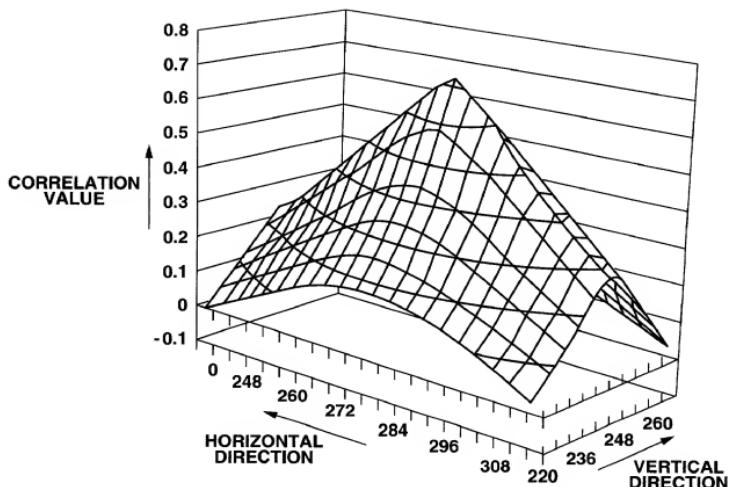


FIG.17

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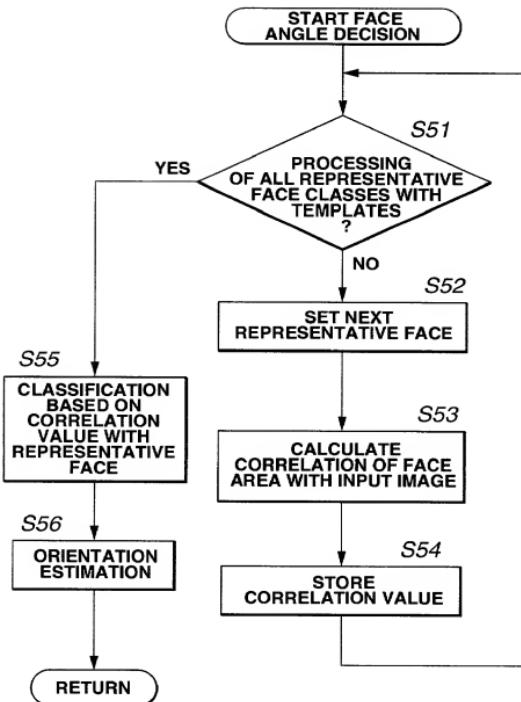


FIG.18

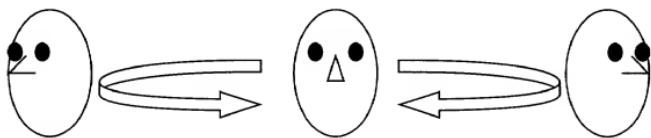
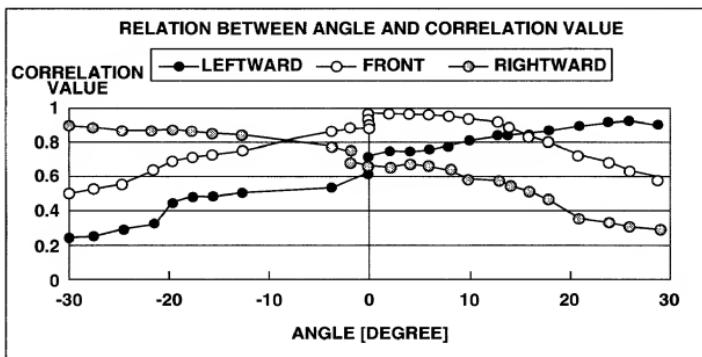
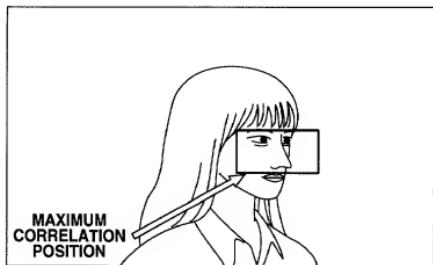
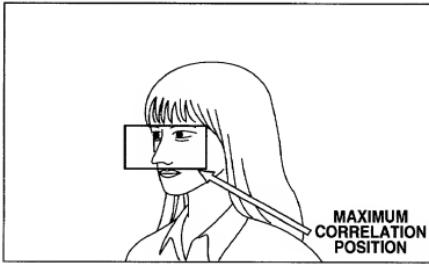


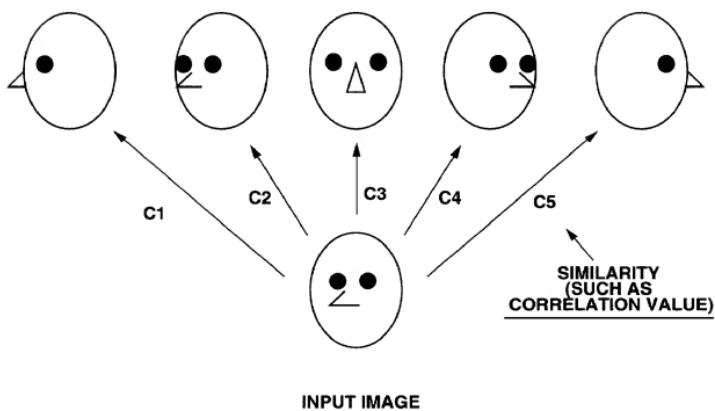
FIG.19



**FIG.20**



**FIG.21**

REPRESENTATIVE FACES OF FACE CLASS**FIG.22**

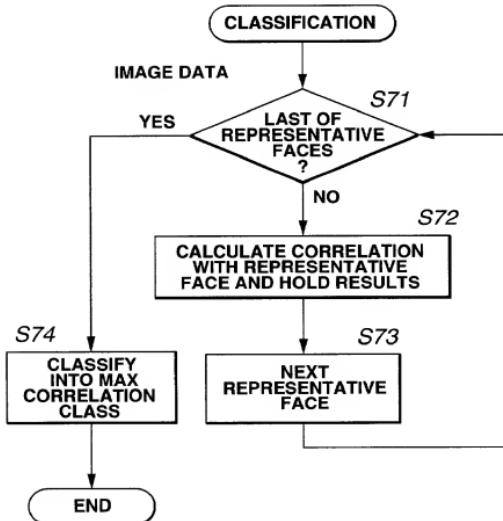


FIG.23

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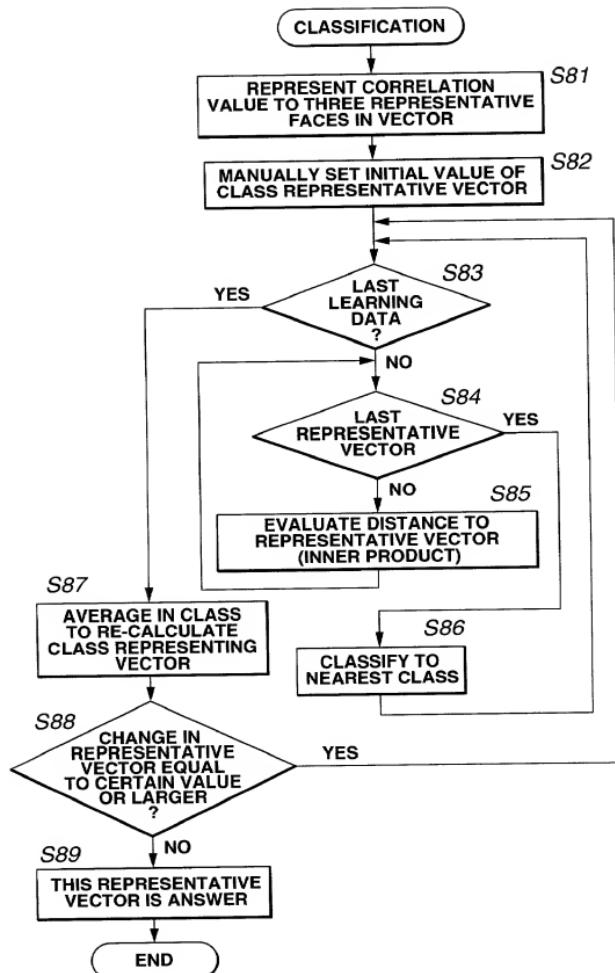
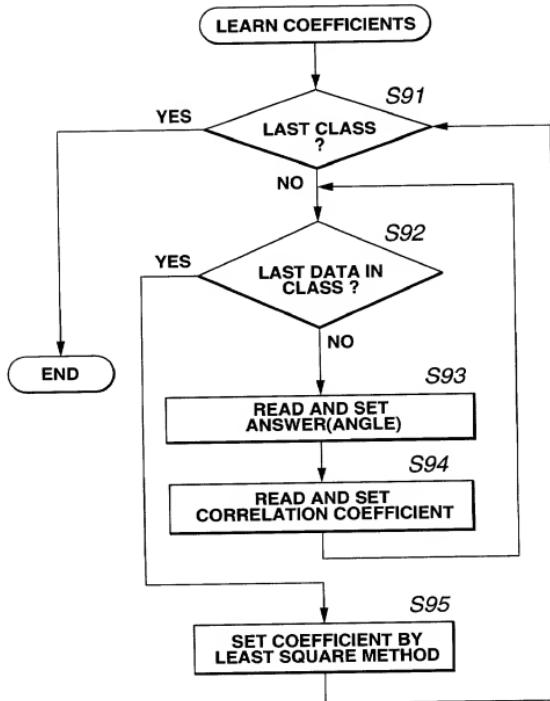
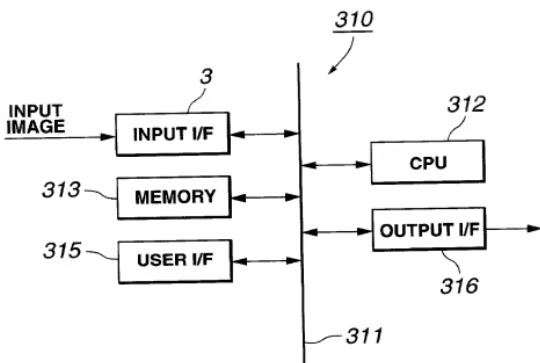


FIG.24

**FIG.25**

**FIG.26**

## Declaration and Power of Attorney for Patent Application

## 特許出願宣言書及び委任状

## Japanese Language Declaration

## 日本語宣言書

私は、以下に記名された発明者として、ここに下記の通り宣言する：

As a below names inventor, I hereby declare that:

私の住所、郵便の宛先そして国籍は、私の氏名の後に記載された通りである。

My residence, post office address and citizenship are as stated next to my name:

下記の名前の発明について、特許請求範囲に記載され、且つ特許が求められている発明主創に關して、私は、最初、最先且つ唯一の発明者である（第一の氏名が記載されている場合）か、或いは最初、最先且つ共同発明者である（複数の氏名が記載されている場合）と信じてている。

I believe I am the original, first and sole inventor(if only one name is listed below) or an original, first and joint inventor (if plural names are listed below) of the subject matter which is claimed and for which a patent is sought on the invention entitled.

DATA PROCESSING APPARATUS, DATA PROCESSING METHOD AND RECORDING MEDIUM

上記明細書はここに添付されているが、下記の都がチェックされている場合は、この限りでない：

       の日に出願され、  
この出願の米国出願番号またはPCT国際出願番号は、  
      であり、且つ  
      の日に補正された出願（該当する場合）

the specification of which is attached hereto unless the following box is checked:

X was filed on March 13, 2000  
as United States Application Number of  
PCT International Application Number PCT/JP00/01510  
and was amended on  
       (if applicable).

I hereby state that I have reviewed and understand the contents of the above identified specification, including the claims, as amended by any amendment referred to above.

I acknowledge the duty to disclose information which is material to patentability as defined in Title 37, Code of Federal Regulations, Section 1.56.

私は、上記の補正書によって補正された、特許請求範囲を含む上記明細書を檢討し、且つ内容を理解していることをここに表明する。

私は、連邦規則法典第37編規則1.56に定義されている、特許について重要な情報を示す義務があることを認める。

Burden Hour Statement: This form is estimated to take 0.4 hours to complete. Time will vary depending upon the need of the individual case. Any comments on the amount of time you are required to complete this form should be sent to Chief Information Officer, U.S. Patent and Trademark Office, Washington, DC 20231. DO NOT SEND FEES OR COMPLETED FORMS TO THIS ADDRESS. SEND TO: Commissioner of Patents and Trademarks, Washington, DC 20231.

## Japanese Language Declaration

## 日本語宣言書

私は、ここに、以下に記した外国での特許出願または発明者証の出願、或いは米国以外の少なくとも一国を指定していざる米国法典第35編第3.65条(e)によるPCT国際出願について、第119条(e)項第3.65条(n)項に基づく優先権を主張する。とともに、優先権を主張する本出願の出願日よりも前の出願日を有する外国での特許出願または発明者証の出願、或いはPCT国際出願については、いかなる出願も、下記の件内をチェックすることによりました。

## Prior Foreign Application(s)

## 外国での先行出願

11-066635

(Number)  
(番号)Japan  
(Country)  
(国名)

PCT/JPOO/01510

(Number)  
(番号)PCT  
(Country)  
(国名)(Number)  
(番号)(Country)  
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(番号)(Country)  
(国名)(Number)  
(番号)(Country)  
(国名)

私は、ここに、下記のいかなる米国特許出願についても、その米国法典第35編第119条(e)項の利益を主張する。

(Application No.)

(Filing Date)  
(出願日)

(出願番号)

私は、ここに、下記のいかなる米国出願についても、その米国法典第35編第120条に基づく利益を主張し、又はそれを指定するいかなるPCT国際出願についても、その米国法典第3.65条(e)に基づく利益を主張する。また、本出願の各特許請求の範囲の主張は、米国法典第35編第112条第1段に規定された趣旨で、先行する米国出願又はPCT国際出願においてい場合においては、その先行出願の出願日と本米国出願日またはPCT国際出願日の期間の間に入手された情報で、遡及規則法典第37編規則1.5.6に定義された特許性に関わる重要な情報について示す趣旨があることを承認する。

(Application No.)  
(出願番号)(Filing Date)  
(出願日)

私は、ここに表明された私自身の知曉に係わる種述が真実であり、且つ特權と信じることに基づく種述が、実質であると信じられる内容を宣言し、さらに、故意に虚偽の種述などを行った場合は、米国法典第18編第1001条に基づき、罰金または拘禁、若しくはその四方により追跡され、またそのような故意による虚偽の種述は、本出願またはそれに対して発行されるいかなる特許も、その有効性に問題を生ずることを理解した上で種述が行われたことを、ここに宣言する。

I hereby claim foreign priority under Title 35, United States Code, Section 119(a)-(d) or 365(b) of any foreign application(s) for patent or inventor's certificate, or 365(a) of any PCT International application which designated at least one country other than the United States listed below and have also identified below, by checking the box, any foreign application for patent or inventor's certificate or PCT international application having a filing date before that of the application for which priority is claimed.

Priority Not Claimed

優先権主張なし

12 March 1999  
(Day/Month/Year Filed)13 March 2000  
(Day/Month/Year Filed)

(Day/Month/Year Filed)



(Day/Month/Year Filed)



(Day/Month/Year Filed)



(Day/Month/Year Filed)



I hereby claim the benefit under Title 35, United States Code, Section 119(e) of any united States provisional application(s) listed below.

(Application No.)  
(出願番号)(Filing Date)  
(出願日)

I hereby claim the benefit under Title 35, United States Code, Section 120 of any United States application(s), or 365D of any PCT international application designating the United States, listed below and, insofar as the subject matter of each of the claims of this application is not disclosed in the prior United States or PCT International application in the manner provided by the first paragraph of Title 35, United States Section 112, I acknowledge the duty to disclose information which is material to patentability as defined in Title 37, Code of Federal Regulations, Section 1.56 which became available between the filing date of the prior application and the national or PCT international filing date of application.

(Status: Patented, Pending, Abandoned)  
(現況: 特許許可、係置中、放棄)

I hereby declare that all statements made herein of my own knowledge are true and that all statements made on information and belief are believed to be true; and further that these statements were made with the knowledge that willful false statements and the like so made are punishable by fine or imprisonment, or both, under Section 1001 of Title 18 of the United States Code and that such willful false statements may jeopardize the validity of the application or any patent issued thereon.

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委任状： 私は本出願を審査する手続を行い、且つ米国特許商標局との全ての業務を遂行するために、把名された発明者として、下記の弁護士及び/または弁理士を任命する。（氏名及び登録番号を記載すること）

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郵便の宛先

POWER OF ATTORNEY: As a named inventor, I hereby appoint the following attorney(s) and/or agent(s) to prosecute this application and transact all business in the Patent and Trademark Office connected therewith (list name and registration number)

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